

rotor groove 60B. The stator 10 has a fixed connection surface 35 disposed between the front stator groove 31 and the back stator groove 38, in which the fixed connection surface 35 connects between the front stator groove 31 and the back stator groove 38. The front stator groove 31 and the fixed connection surface 35 and the fixed connection surface 35 and the back stator groove 38 may each be formed at an obtuse angle.

[0066] A width W4 of the fixed connection surface 35 may have an interval equal to or larger than the width W3 of the teeth body 21. In an electric motor 100 having eight poles and twelve slots according to the exemplary embodiment of the present disclosure, $W4 \geq W3$ may be preferable in the efficiency of the electric motor 100 and the width W4 of the fixed connection surface 35 may be smaller than that of the teeth body 21 according to the number of slots. For example, in the electric motor having six slots, the width of the fixed connection surface 35 may be smaller than that of the teeth body 21.

[0067] A width W2 of the front rotor groove 60A may have an interval larger than a width W1 of the front stator groove 31. The front and back stator grooves 31 and 38 may have a curvature radius equal to that of the front and back rotor grooves 60A and 60B.

[0068] An angle $\theta 5 - \theta 1$ between a front end of the front rotor groove 60A and a back end of the front rotor groove 60A is larger ($\theta 5 - \theta 1 > \theta 4 - \theta 6$) than an angle $\theta 4 - \theta 6$ between a front end of the front stator groove 31 and a back end of the front stator groove 31, based on a virtual line L that connects between a center C of the rotor and a center of the teeth part 20. That is, the front stator groove 31 has a smaller separation distance than the front rotor groove 60A and is received in the front rotor groove 60A. The front rotor groove 60A and the back rotor groove 60B may be symmetrical to each other with respect to the bridge part 55.

[0069] An angle $\theta 4$ of the front end of the front stator groove 31 and the virtual line L is larger than an angle $\theta 2$ of the front end of the fixed connection surface 35 and the virtual line L, based on the virtual line L that connects between the center of the rotor 40 and the center of the teeth part 20. The front stator groove 31 and the back stator groove 38 may be symmetrical to each other with respect to a center of the fixed connection surface 35.

[0070] That is, an air gap may be formed between the rotor 40 and the stator 10. The air gap may have a first air gap part 32 formed between the rotating connection surface 65 and the fixed connection surface 35 opposing thereto and second air gap parts 33A and 33B that are each formed at an outside of the first air gap part 32, e.g., at a central portion of the air gap. The second air gap parts 33A and 33B may be formed to have a larger interval than the first air gap part 32 by the front stator groove 31 and the front rotor groove 60A and the back stator groove 38 and the back rotor groove 60B.

[0071] FIG. 6 is an exemplary cross-sectional view of a second exemplary embodiment of the electric motor illustrated in FIG. 1 and FIG. 7 is an enlarged view of the stator illustrated in FIG. 6. In FIGS. 6 and 7, a difference from the foregoing electric motor is described but the omitted description may be replaced by the foregoing content. As illustrated in FIGS. 6 and 7, the rotor 40 has the bridge part 55 disposed between poles. A front and a back of the bridge part 55 with respect to the rotating direction of the rotor 40 are provided with the front rotor groove 60A and the back rotor groove 60B that are each dented.

[0072] The stator 10 has the front stator groove 31 and the back stator groove 38 that are each dented from the inner surfaces each facing the front rotor groove 60A and the back rotor groove 60B. The front stator groove 31 may have first and second front stator grooves 31A and 31B. The first front stator groove 31A may be disposed at the front with respect to the rotating direction of the rotor 40. A second front stator groove 31B may be disposed at the back of the first front stator groove 31A and protrudes from the first front stator groove 31A.

[0073] The back stator groove 38 may have first and second back stator grooves 38B and 38A. The first back stator groove 38B is disposed at the back with respect to the rotating direction of the rotor 40. A second back stator groove 38A is disposed at the front of the first back stator groove 38B and protrudes from the first back stator groove 38B. That is, the first front stator groove 31A and the first back stator groove 38B and the second front stator groove 31B and the second back stator groove 38A may each be symmetrical to each other with respect to the virtual line L connecting between the center of the rotor 40 and the center of the teeth part 20.

[0074] An angle $\theta 2$ of a back end of the second front stator groove 31B and the virtual line L may be equal to or larger than an angle $\theta 1$ of a back end of the front rotor groove 60A and the virtual line L, based on the virtual line L connecting between the center of the rotor 40 and the center of the teeth part 20. An angle $\theta 5$ of a front end of the first front stator groove 31A and the virtual line L is larger than an angle $\theta 4$ of the front end of the front rotor groove 60A and the virtual line L.

[0075] The angle $\theta 4$ of the front end of the first front rotor groove 60A and the virtual line L is larger than an angle $\theta 3$ of the front end of the second front stator groove 31B and the virtual line L, in which the angle $\theta 3$ is larger than the angle $\theta 2$ of the back end of the second front stator groove 31B and the virtual line L. That is, $\theta 1 \leq \theta 2 < \theta 3 < \theta 4 < \theta 5$.

[0076] FIG. 8 is a diagram illustrating the existing electric motor. Generally, a brushless direct current motor does not include a brush and a commutator but includes an electronic commutation mechanism, such that mechanical or electrical noise may not be caused, a motor having various speeds from low speed to high speed may be manufactured, a rotating torque may be stable due to a multi pole, and a long-life electric motor may be simply manufactured.

[0077] The stator of the existing brushless direct current motor is configured to include a plurality of teeth protruding on an inner circumferential surface thereof, concave slots formed between the respective teeth, a stator core having a slot opening formed between the respective tips protruding at both ends of the teeth, and coils wound around both slots of the teeth of the stator core.

[0078] Air gaps between a stator 70 and a rotor 80 have the same interval. In this case, a deviation in magnetic density is large by a magnetic force with a permanent magnet of the rotor 80, and therefore a cogging torque by which the rotor does not generate a uniform torque is caused, such that the motor may vibrate and thus vibration noise may be caused.

[0079] In particular, the air gap that is the interval between the rotor and the stator is preferably designed to be small. In this case, a change in reluctance is large and thus the cogging torque is increased and a torque ripple is also large, which has an adverse effect on the vibration noise.